

Bandpass Negative Group Delay Demonstration on a VHF RLC Parallel Passive Lumped Circuit

Eric Jean Roy Sambatra¹, Yves Constant Mombo Boussougou², Lucius Ramifidisoa³, Jean-Paterne Kouadio⁴, Samuel Ngoho⁴, Antonio Jaomiary³, and Nour Mohammad Murad⁵

¹Institut Supérieur de Technologie (ISTD), BP 509, Antsiranana 201, Madagascar

²Université des Sciences et Techniques de Masuku (USTM), BP 901, Franceville, Gabon

³Ecole Normale Supérieure pour l'Enseignement Technique (ENSET), BP O, Antsiranana 201, Madagascar

⁴Association Française de Science des Systèmes (AFSCET), Paris 75013, France

⁵Energy Lab, Network and Telecom team, Institut Universitaire de Technologie, University of La Reunion, Saint Denis 97715, France

Corresponding author: Eric Jean Roy Sambatra (e-mail: ericsambatra@gmail.com).

ABSTRACT This paper demonstrates the bandpass (BP) negative group delay (NGD) behavior of a passive RLC-parallel lumped network at very high frequencies (VHFs). After topological description, the BP NGD analysis is introduced. The BP NGD circuit is theoretically modelled by means of voltage transfer function (VTF) expression. The analytical equations illustrating the BP NGD specifications as the NGD center frequency, NGD value, NGD bandwidth and VTF attenuation are established in function of the R, L and C component parameters. To verify the relevance of the BP NGD analysis, a lumped circuit proof of concept (POC) is synthesized and designed. As prototype, the corresponding BP NGD circuit prototype of printed circuit board (PCB) is implemented in hybrid technology with SMD components. Then, quite innovated testing method allowing to extract the VTF is developed. As expected, the calculated, simulated and measured results are very well-correlated and showing BP NGD behavior of the POC. The calculated and simulated results with NGD value of - 8 ns (resp. -12 ns), attenuation of - 10 dB (resp. -8 dB) and bandwidth around 225 MHz (resp. 240 MHz) NGD center frequency are obtained. In addition to the experimental validation, uncertainty analysis (UA) with respect to the BP NGD specifications is also studied in order to show the influence of quality and tolerance of lumped components. The theoretical formulas of NGD specification UAs in function of R, L and C tolerances are derived. The UAs with respect to 1%, 2% and 5% relative tolerances of R, L and C components constituting the BP NGD circuit POC are discussed.

INDEX TERMS Negative group delay (NGD), Bandpass (BP) NGD circuit, NGD analysis, RLC parallel (RLCP) topology, lumped passive circuit, very high frequency (VHF), NGD specifications, uncertainty analysis (UA).

I. INTRODUCTION

THE negative group delay (NGD) phenomenon was the first time observed with optical experimentation in 1980s [1-2]. The counterintuitive NGD experimental demonstration attracts the attention of curious physicists in twentieth century. This scientific curiosity leads to deeper investigation for the better understanding about the NGD effect meaning. Therefore, further theoretical investigations were conducted in the optical areas [3-6]. It was found that the NGD effect is materially linked to the negative group velocity (NGV) [3-4]. It is worth to note that the NGV effect are basically evaluated with wave propagating through a resonant and dispersive medium represented by a 1-D or 2-D or 3-D bulk materials. The NGV is analytically

linked to the group refractive index variation of resonant medium.

However, only the material physics approach does not enable to conveniently interpret the NGD effect. Therefore, a typical systemic approach based on the transfer function was introduced [5-8]. By means of the equivalent transfer function, basic topologies of NGD lumped circuit in very low frequencies (VLFs) and in low frequencies (LFs) were proposed in 1990s [7-8]. With such lumped circuits, the NGD signature corresponds to the smoothed signal propagating with output in time advance compared to the corresponding input [7-13]. The asymptotic limits of the NGD effect generated by electronic circuits were reported in [14]. It is noteworthy that the NGD time advance is not in contradiction with the causality [7-10]. Because of this

counterintuitive aspect, the NGD effect remains one of the most unfamiliar effects ever seen in physics area. Curious design and research engineers in 2000s were wondering on the NGD effect existence in the electronics engineering. Different circuit NGD theoretical approaches and experimentations were carried out to answer to this curiosity [7-14].

In parallel with the metamaterial revolution, very high frequency (VHF) and ultra-high frequency (UHF) NGD microwave circuits were designed in 2000s [15-18]. The NGD effect is induced by material with both negative permittivity and negative permeability or also known as double negative index metamaterials [15-18]. These cases of artificial materials are also known as NGV media [15-18]. One of the initial structures allowing to experiment the double negative effect is constituted by split ring resonator (SRR) metamaterial structures [15-18]. Those SRR structures belong to the left-handed periodical circuits. By inspiring with metamaterial-based topologies, transmission line based NGD passive circuits were designed and developed [19-21]. Thanks to the design compactness, tentative applications of NGD circuits were initiated for the improvement of radio frequency (RF) and communication devices as oscillators [22], feedforward amplifiers [23-24], antennas [25-26], non-Foster elements [27-28] and communication device group delay (GD) compensation technique [29-31]. Because of systematic attenuation losses, the performances of NGD passive circuits [15-21] were threatened and less attractive for many electronic engineers. To overcome this critical point of view, some VHF and UHF microwave topologies of NGD active circuits, for example using transistors, were developed [32-35].

Despite, the state of the art on the unfamiliar NGD concept, the NGD effect basic interpretation requires further research effort in order to reach higher level of popularity as the classical electronic functions as filter, amplifier, oscillator and attenuators. So far, one of the ways enabling to interpret in more democratic way the NGD concept is the consideration of the analogy between the filter and NGD behaviors [35]. In function of the NGD bandwidth positioning, the innovative concept of bandpass (BP) NGD function was introduced [35]. So far, as the meaning of BP NGD circuit is still not understandable to most of electronic designers and manufacturers. We propose a quite easy to understand and didactical research work about BP NGD circuit engineering opens to non-specialists as graduated students, technicians and engineers in the present article. The two main bullets of research contributions of the article are:

- A BP NGD characterization of RLC parallel based lumped passive network topology;
- And a special focus on the open question about the robustness of BP characteristic uncertainty analysis (UA) versus the R, L and C component tolerances.

The present research work paper is organized in six different sections as follows:

- Section II defines the main specifications of the unfamiliar BP NGD function. After the introduction of the considered passive topology, the main parameters characterizing the BP NGD responses are analytically defined.
- Section III introduces the BP NGD analysis of the considered passive topology based on RLC parallel (RLCP) passive network. After the frequency response expressions, the NGD parameters will be established in function of the R, L and C ones.
- Section IV develops a figure of merit (FoM) expression of the BP NGD circuit. The BP FoM optimality will be formulated.
- Section V is focused on the corroborated validation results of calculation, simulation and measurement. The validation of the BP NGD aspect is performed by designing a proof of concept (POC) and PCB prototype composed of lumped components. Then, the BP NGD specifications from analytical calculations, simulations and experimentations are discussed.
- Section VI is innovatively focused on the UA investigation. The aim of this study is to show the influence of quality and tolerance of components for NGD circuit. The UAs of the BP NGD specifications will be literally expressed and numerically verified with respect to the constituting component tolerances.
- Then, Section VII addresses the final conclusion.

II. FUNDAMENTAL SPECIFICATIONS OF THE UNFAMILIAR BP NGD FUNCTION

For the better understanding on the unfamiliar BP NGD function, it is necessary to recall the definition of basic BP NGD parameters [35-36]. This preliminary definition is based on the voltage transfer function (VTF) expression of the considered passive topology.

A. DEFINITION OF BP NGD SPECIFICATIONS

Let us consider the black box of two-port circuit shown in Fig. 1. By denoting the input voltage V_{in} and the output voltage V_{out} , according to the circuit and system theory, the VTF of the circuit in the frequency domain can be expressed by:

$$T(j\omega) = \frac{V_{out}(j\omega)}{V_{in}(j\omega)} \quad (1)$$

with the angular frequency complex variable $j\omega$.

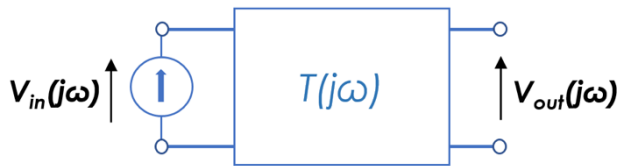


FIGURE 1. Black box diagram with VTF.

The basic elements to explore the BP NGD response of our circuit are the magnitude $T(\omega)$, and the phase, $\psi(\omega)$ which are respectively given by:

$$T(\omega) = |T(j\omega)| \quad (2)$$

$$\psi(\omega) = \arg[T(j\omega)] \quad (3)$$

According to circuit theory, the GD derived from this last expression is defined by the following equation:

$$GD(\omega) = -\frac{\partial\psi(\omega)}{\partial\omega} \quad (4)$$

The BP NGD function depends on the sign of the GD and the frequency band position where it presents negative sign.

B. GRAPHICAL DIAGRAM ILLUSTRATING BP NGD SPECIFICATIONS

The BP NGD analysis of our RLCP passive topology must be performed with respect to specific parameters linked to the frequency responses. Doing this, we refer the BP NGD specifications with the ideal magnitude and GD diagrams of Figs. 2.

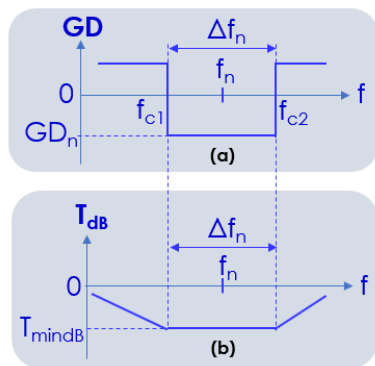


FIGURE 2. Graphical NGD specifications: (a) GD and (b) magnitude.

In this case of study, in difference to most of classical electronics circuit, the main parameters of the characterization are essentially the GD and the magnitude. Subsequently, Fig. 2(a) and Fig. 2(b) introduce ideal plots associated to the GD and magnitude characterizing the unfamiliar BP NGD responses versus positive real frequency traditionally known as:

$$f = \frac{\omega}{2\pi} \quad (5)$$

As illustrated in Fig. 2(a), the ideal GD response of the BP NGD circuit should respect the conditions:

$$GD(\omega_{c1} < \omega < \omega_{c2}) \approx GD_n < 0 \quad (6)$$

$$GD(\omega < \omega_1 \cup \omega_2 < \omega) > 0 \quad (7)$$

In this analytical configuration, we denote the NGD center frequency:

$$\omega_n = 2\pi f_n \quad (8)$$

and the NGD cut-off frequencies:

$$\omega_k = 2\pi f_k \quad (9)$$

with $k = \{1,2\}$. These specific frequencies are related to the GD values following the mathematical equation and inequation defined respectively by:

$$GD(\omega_k) = 0 \quad (10)$$

$$GD(\omega_n) < 0 \quad (11)$$

The NGD bandwidth is equal to:

$$\begin{cases} \Delta\omega_n = \omega_2 - \omega_1 \\ BW_{NGD} = \frac{\Delta\omega_n}{2\pi} = f_2 - f_1 \end{cases} \quad (12)$$

As seen in Fig. 2(b), in the frequency band, $\omega_1 < \omega < \omega_2$, the attenuation losses must respect the classical constraints related to T_{\min} as classical microwave devices:

$$|T(j\omega)| \geq T_{\min} \quad (13)$$

Similar to classical electronic functions as filters, amplifiers, oscillators and many more, the design engineering starting from ideal specification diagrams must be followed by concrete materialization. Therefore, a circuit topology is required.

In this optic, the unfamiliar BP NGD function is concretized by circuit theory of RLCP passive cell introduced in the following section.

III. BP NGD ANALYSIS OF THE CONSIDERED RLC PARALLEL (RLCP) PASSIVE TOPOLOGY

The present section develops the VTF based BP NGD analysis of the topology representing lumped passive cell under study. The analytical specification is established in function of the circuit parameters.

A. TOPOLOGICAL INTRODUCTION AND VTF EXPRESSION OF THE RLCP CIRCUIT

Fig. 2 represents the RLCP network-based topology under study which is represented by passive parallel network comprised of components, resistance, R_n , inductance, L_n and capacitor, C_n . The proposed passive cell scheme input is connected to voltage source, V , corresponding to input voltage, V_{in} .

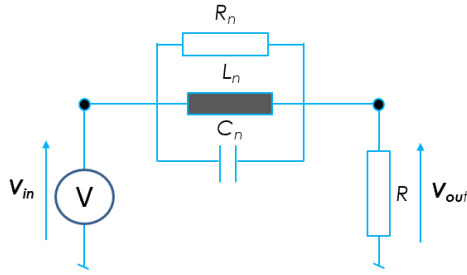


FIGURE 3. RLCP network-based BP NGD passive cell under study.

Moreover, the circuit output, generating output voltage, V_{out} , is connected to shunt resistance, R . In brief, we have in the lumped passive cell scheme, input voltage V_{in} and output voltage V_{out} across resistance R . By means of this scheme, we can define a series complex impedance consisted of R_n , L_n and C_n parallel components:

$$Z(j\omega) = \frac{1}{\frac{1}{R_n} + \frac{1}{j\omega L_n} + j\omega C_n} \quad (14)$$

Before the analytical development, we can express the VTF is defined by equation (1) by using the voltage divider principle. It can be demonstrated that this VTF can be explicitly rewritten in function of the RLC component parameters by:

$$T(j\omega) = \frac{R[L_n\omega + jR_n(L_nC_n\omega^2 - 1)]}{(R + R_n)L_n\omega + jR_nR(L_nC_n\omega^2 - 1)} \quad (15)$$

From this VTF, we can express the previously introduced NGD characteristics in function of the component parameters in the next subsection.

B. BP NGD CHARACTERISTICS OF THE CONSIDERED PASSIVE TOPOLOGY

By considering the main quantities of BP NGD frequency responses defined earlier in equations (2), (3) and (4), the magnitude associated to the VTF defined in equation (15) can be given by:

$$T(\omega) = \frac{R\sqrt{(L_n\omega)^2 + [R_n(L_nC_n\omega^2 - 1)]^2}}{\sqrt{[(R_n + R)L_n\omega]^2 + [R_nR(L_nC_n\omega^2 - 1)]^2}} \quad (16)$$

By definition (3), the corresponding phase response is equal to:

$$\psi(\omega) = \psi_1(\omega) + \psi_2(\omega) \quad (17)$$

with:

$$\psi_1(\omega) = \arctan\left[\frac{R_n}{L_n\omega}(L_nC_n\omega^2 - 1)\right] \quad (18)$$

$$\psi_2(\omega) = \arctan\left[\frac{R_nR}{L_n\omega(R_n + R)}(1 - L_nC_n\omega^2)\right] \quad (19)$$

According to equation (4), the GD is formulated as:

$$GD(\omega) = GD_1(\omega) + GD_2(\omega) \quad (20)$$

with:

$$\begin{cases} GD_1(\omega) = -\frac{\partial\psi_1(\omega)}{\partial\omega} \\ GD_2(\omega) = -\frac{\partial\psi_2(\omega)}{\partial\omega} \end{cases} \quad (21)$$

which implies:

$$GD_1(\omega) = \frac{\frac{R_n}{L_n\omega^2}(L_nC_n\omega^2 - 1) - 2R_nC_n}{1 + \left[\frac{R_n}{L_n\omega}(L_nC_n\omega^2 - 1)\right]^2} \quad (22)$$

$$GD_2(\omega) = \frac{\frac{R_nR}{L_n(R_n + R)\omega^2}(1 - L_nC_n\omega^2) + \frac{2R_nRC_n}{R_n + R}}{1 + \left[\frac{R_nR}{L_n\omega(R_n + R)}(L_nC_n\omega^2 - 1)\right]^2} \quad (23)$$

These frequency responses constitute the background of the BP NGD analysis by establishing the basic specifications. The following subsections express these specifications with respect to the R, L and C component parameters.

C. NGD CENTER FREQUENCY AND BANDWIDTH

We recall that the NGD bandwidth, denoted, BW_{NGD} is given in relation (12). To determine this parameter, the approach consists of finding the roots of equation (12). The NGD center frequency previously given in equation (21) is also classically known as the resonance frequency:

$$\omega_n = \frac{1}{\sqrt{L_nC_n}} \quad (24)$$

of $R_nL_nC_n$ network of our passive topology introduced in Fig. 3. This center frequency is linked to the capacitor parameter design equation:

$$C_n = \frac{1}{\sqrt{L_n\omega_n^2}} \quad (25)$$

Thus, the mathematical simplification leads us to the solutions of the following equation:

$$L_n^2C_n^2\omega^4 - L_n\left(2C_n + \frac{L_n(R_n + R)}{R_n^2R}\right)\omega^2 + 1 = 0 \quad (26)$$

Therefore, the roots of this equation which represent the cut-off frequencies are:

$$f_{c_1} = \frac{\sqrt{2C_n + \frac{L_n(R_n + R)}{R_n^2R} - \sqrt{\left(2C_n + \frac{L_n(R_n + R)}{R_n^2R}\right)^2 - 4C_n^2}}}{2\pi C_n \sqrt{2L_n}} \quad (27)$$

and:

$$f_{c_2} = \frac{\sqrt{2C_n + \frac{L_n(R_n + R)}{R_n^2 R}} + \sqrt{\left(2C_n + \frac{L_n(R_n + R)}{R_n^2 R}\right)^2 - 4C_n^2}}{2\pi C_n \sqrt{2L_n}} \quad (28)$$

These two frequencies are chosen by supposing:

$$f_{c_1} < f_{c_2} \quad (29)$$

The NGD bandwidth is taken from equation (12) as:

$$BW_{NGD} = f_{c_2} - f_{c_1} \quad (30)$$

At this step, the calculation of the product of the two frequencies makes possible further understanding about symmetrical aspect of the PB NGD GD response. Indeed, from equations (27) and (28), it can be analytically verified that:

$$f_{c_1} f_{c_2} = f_n^2 \quad (31)$$

This last relation proves that our BP NGD response is symmetrical with respect of f_n .

D. SPECIFIC NGD PARAMETER EXPRESSIONS AT THE NGD CENTER FREQUENCY

First of all, we remind that the main goal of the study is to analyze the behavior of the RLCP topology under study around the NGD center frequency. The specifications such as the VTF magnitude and GD can be evaluated in function of this frequency. Therefore, substituting the frequency variable with equation (24) into magnitude given in relation (10), we have:

$$T_n = T(\omega_n) = \frac{R}{R_n + R} \quad (32)$$

Following the same way, we have:

$$GD_n = GD(\omega_n) \quad (33)$$

By means of the GD expressed in equation (21), the last equation can be detailed as:

$$GD_n = \frac{-2R_n^2}{L_n \omega_n^2 (R_n + R)} \quad (34)$$

Then, the NGD bandwidth proposed in equation (30) becomes:

$$BW_{NGD} = \frac{\sqrt{1 + \frac{R_n}{R}}}{2\pi C_n R_n} \quad (35)$$

Knowing these BP NGD parameters, we may wonder about the performance criteria. The following section is dedicated to the deep study on the BP NGD figure of merit (FoM).

IV. BP NGD RLCP PASSIVE TOPOLOGY FIGURE OF MERIT

The present section elaborates the FoM of our BP NGD topology. The mathematical expression of the BP NGD

FoM will be defined. Then, the optimal case will be discussed.

A. BP NGD FIGURE OF MERIT

To assess the performances of the BP NGD circuit under study, a figure of merit (FoM) has been defined as a product of the circuit NGD parameters previously established at the NGD frequency f_n . The FoM is expressed by:

$$FoM_n = -T_n \cdot BW_{NGD} \cdot GD_n \quad (36)$$

By replacing BW_{NGD} and GD_n by their respective expressions at f_n , the previous formula becomes:

$$FoM_n = \frac{(1 - T_n) \sqrt{T_n}}{\pi} \quad (37)$$

By taking into account the expression of T_n at f_n , we can demonstrate that our FoM depends only on the resistive elements of the RLCP circuit.

B. OPTIMAL VALUE OF BP NGD FoM

The optimal value of the FoM is obtained from the derivation with respect to the minimal magnitude:

$$\frac{\partial FoM_n}{\partial T_n} = 0 \quad (38)$$

It can be analytically demonstrated that the derived magnitude optimal value is equal to:

$$T_n = \frac{1}{3} \quad (39)$$

Substituting this last value into equation (37), we obtain the maximum value of FoM_n equal to:

$$|FoM_n|_{\max} = \frac{2}{3\sqrt{3}\pi} \quad (40)$$

C. GRAPHICAL ANALYSIS OF BP NGD FoM

Fig. 4 represents the respective shapes of FoM_n and of the ratio of resistances R_n/R as a function of T_n at the NGD center frequency f_n . With respect to the FoM_n variational behavior, we identify three areas:

- $T_n \in]0; 0.2]$: Strong variation of FoM_n for about one-sixth of the span of T_n .
- $T_n \in]0.2; 0.5]$: Weak variation of FoM_n for about a third of the span of T_n .
- $T_n \in]0.5; 1[$: Significant variation in FoM_n over about half the span of T_n .

Thus, the choice of resistors should be made in zone II of FoM_n . On the other hand, the resistance ratio can be divided into two areas:

- $T_n \in]0; 0.03]$: Significant change in R_n/R during a very short range of T_n (about 1/30).
- $T_n \in]0.03; 1[$: Small change in R_n/R for about one third of the span of T_n .

It is found that during the intersection in zone II of FoM_n and R_n/R , the slightest variation in the resistance ratio can induce a remarkable variation in FoM_n .

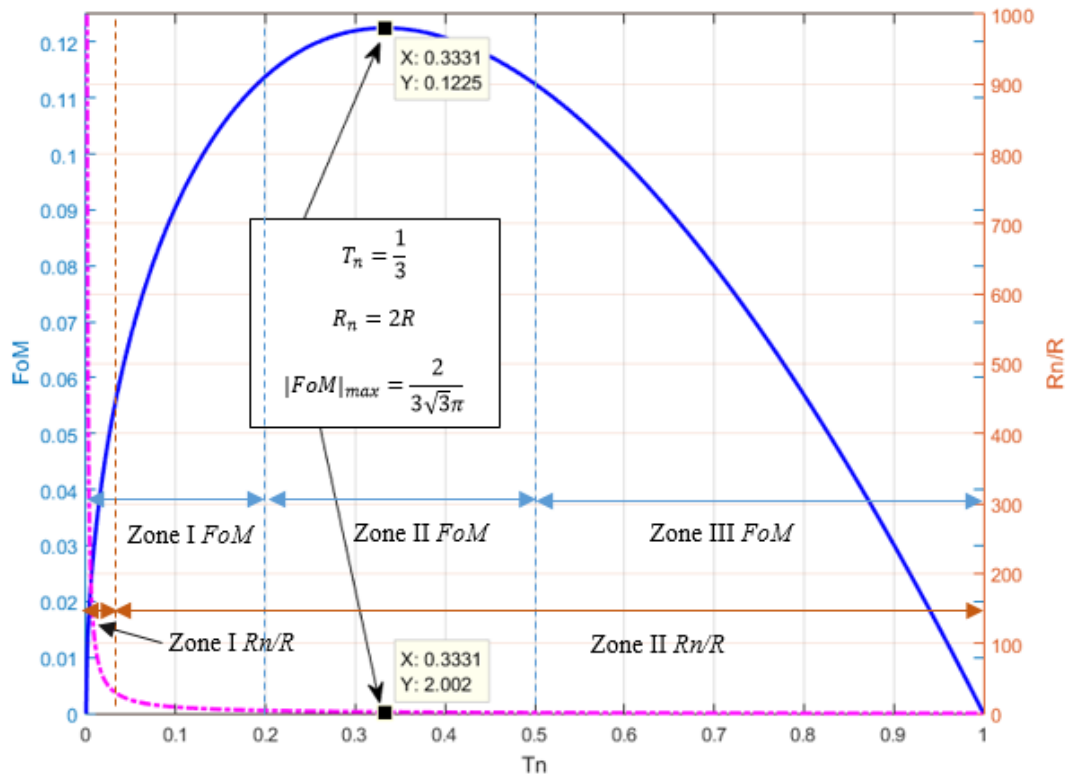


FIGURE 4. FoM_n and R_n/R ratio variations vs T_n .

This combination of representation serves to choose relevant values of resistors maximizing FoM_n .

To verify the validity of the developed BP NGD analysis of RLCP topology, results of POC, prototype demonstrator, simulation and experimentation will be discussed in the following section.

V. BP NGD BEHAVIOR VALIDATION

The present section focuses on the BP NGD validation of the RLCP passive topology under study. The frequency responses calculated from MATLAB® are compared to the simulation model and the measured prototype.

A. DESIGN DESCRIPTION OF THE BP NGD CIRCUIT POC

The validation approach is based on the comparison between the MATLAB® numerical computation of analytical expressions given in equations (17), (18) and (21) with the simulation and measurement results.

The BP NGD design of the RLCP electronic circuit POC can be performed by the following steps:

- Step 1: Choice of BP NGD specifications (as indicated in the ideal diagrams of Fig. 2)
- Step 2: Calculations of the constituting R, L and C component ideal values constituting the circuit
- Step 3: Choice of available nominal components
- Step 4: UA analysis by taking into account the component tolerances.

These different steps of BP NGD circuit can be realized by non-specialist electronic engineering amateurs and also students.

The circuit design was made by choosing the NGD center frequency f_n of about 240 MHz. As revealed by equation (40), the maximum expression of FoM is reached by choosing resistance values with respect to the relationship $R_n = 2R$. After fixing the values of f_n , R_n , R and L_n , the value of C_n was determined by relation (24).

Table I summarizes the fixed and calculated parameters of the POC RLCP circuit. The frequency domain or AC simulation of VTF was carried out with the commercial tool of electronic circuit simulator ADS® from Keysight Technologies®.

TABLE I. Parameters of the RLCP Circuit POC

Parameter	Value
f_n	240 MHz
R	150 Ω
R_n	300 Ω
L_n	22 nH
C_n	20 pF

Fig. 4(a) illustrates the ADS schematic design of the RLCP circuit. Fig. 4(b) displays the fabricated RLCP PCB prototype implemented in hybrid technology. The tested BP NGD PCB is fabricated with R, L and C surface mounted devices (SMDs).

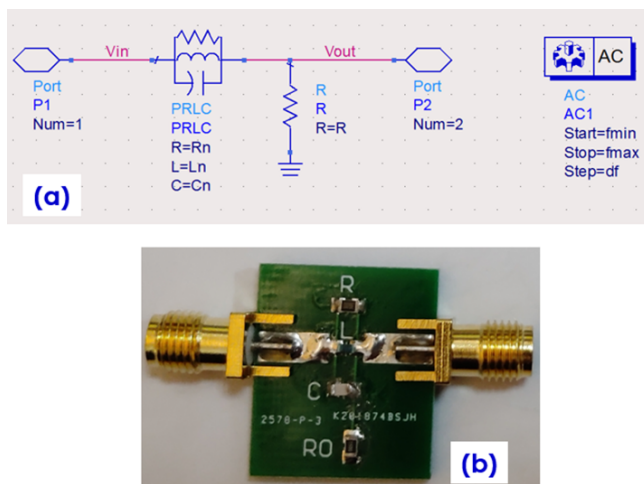


FIGURE 5. (a) POC ADS® design and (b) prototype photograph of NGD passive RLCP circuit.

To validate the BP NGD behavior with the PCB prototype, measurement test campaign was made. The following subsection briefly describes the experimental setup.

B. EXPERIMENTAL INVESTIGATION

First and foremost, as revealed in the previous design section, our BP NGD demonstrator is implemented as a two-port circuit expected to operate hundred-megahertz frequency range.

We remind that the present experimental investigation is based on the RLCP circuit under test (CUT) shown in Fig. 4(b). The experimentation was performed with S-parameters measurement as proposed in [36]. The photograph of the experimental setup including the BP NGD circuit prototype is illustrated by Fig. 6. We can see that the test setup of the BP NGD circuit measurement was performed by connecting the circuit input and output to a vector network analyzer (VNA). The employed VNA is referenced Rohde&Schwarz® ZNB 20 and able to operate in a 100 kHz - 20 GHz frequency band.

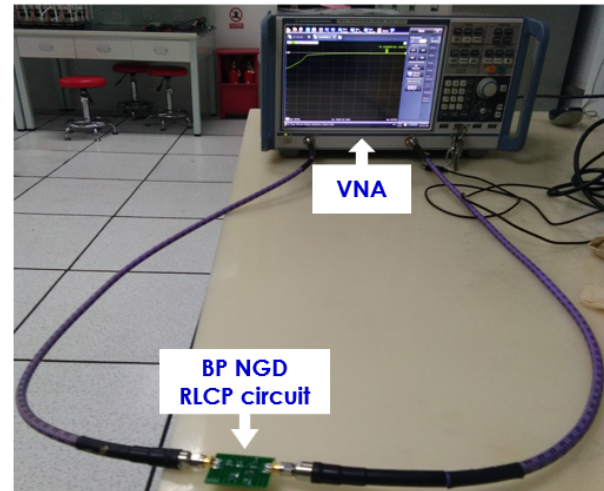


FIGURE 6. Experimental setup photograph of the BP NGD RLCP circuit prototype

As a matter of fact, the obtained validation results of BP NGD responses will be discussed in the following subsection.

C. COMPARATIVE STUDY OF THE CALCULATED, SIMULATED AND EXPERIMENTED BP NGD RESPONSES

Table II highlights the expected BP NGD specifications of our demonstrator. In order to verify the BP NGD aspect with the considered POC and demonstrator, the frequency band of the present comparative study is performed within the limits $f_{min}=140$ MHz to $f_{max}=360$ MHz.

TABLE II. Targeted BP NGD Specifications

Parameter	Value
f_n	240 MHz
f_{e1}	220.42 MHz
f_{e2}	261.18 MHz
BW_{NGD}	40.76 MHz
GD_n	-10.47 ns
FoM	0.1224

As results of our BP NGD study, Figs. 7 represent the comparisons of the frequency domain or AC responses from the POC and demonstrator of RLCP circuit introduced earlier in Figs. 4. The blue solid, cyan dashed and pink dot-dashed curves are calculated (“Theory”), simulated (“Simulation”) and measured (“Measure”) results, respectively. It is plotted in top, middle and bottom of Figs. 7 the magnitude, phase and GD diagrams of our RLCP circuit POC and prototype. We can point out from these plots that the simulated VTF results are very well-correlated to the calculated ones. However, notable differences with those two ones are observed for the cases of measurement. Such deviations can be hypothetically explained due:

- To the PCB prototype fabrication imperfection;
- To the measurement systematic errors as the parasitic effects from connectors, cables and VNA itself;
- And in particular, the uncertainties linked to the R, L, and C component tolerances in the considered working frequency band.

Table III summarizes the BP NGD specifications as NGD center frequency f_n , NGD cut-off frequencies $f_{c1,2}$,

NGD bandwidth BW , attenuation T_n and NGD value GD_n associated to the theoretical, simulated and measured approaches. We can clearly underline by looking at the bottom of Fig. 7 that the considered RLCP topology behaves as a BP NGD function in the working frequency band. The calculated and simulated GD diagrams reveal NGD value of about -10.63 ns while the experimented one is of about -8.1 ns.

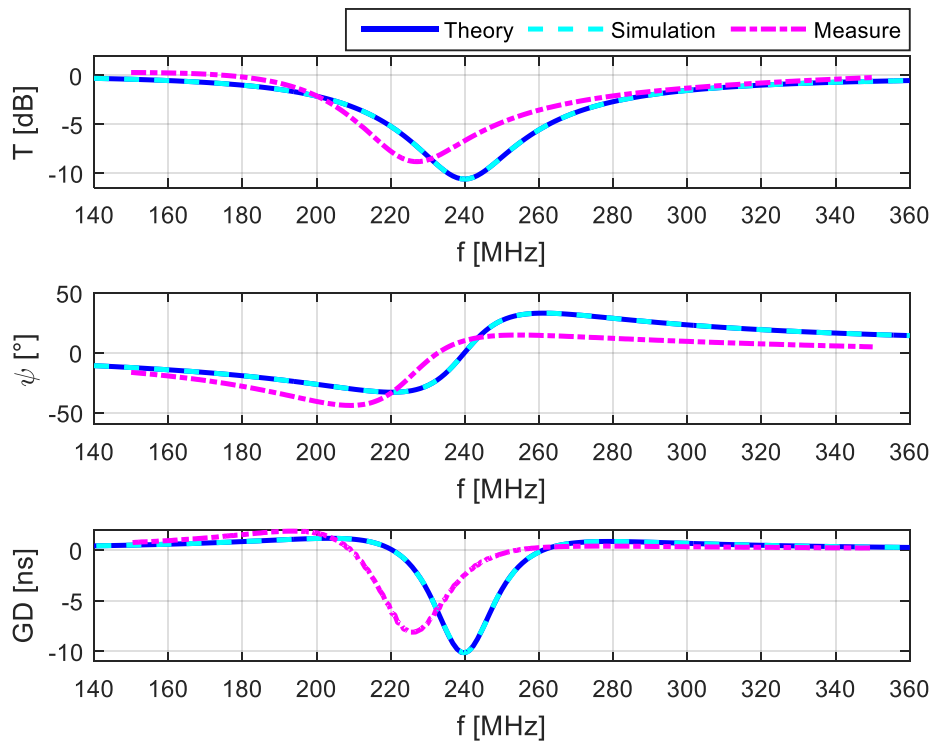


FIGURE 7. Comparison between calculated, simulated and measured (a) magnitudes, (b) phases and (c) GDs of the BP NGD circuit demonstrator shown in Figs. 4.

TABLE III. Comparison between the calculated and simulated NGD parameters

Approach	f_n (MHz)	f_{c1} (MHz)	f_{c2} (MHz)	BW (MHz)	T_n (dB)	GD_n (ns)	FoM
Theory	240.1	219.8	261.6	41.8	-10.629	-10.155	0.1248
Simulation	239.6	218.7	259.4	41.3	-10.63	-10.15	0.1232
Measurement	227.1	209	253.2	44.2	-8.84	-8.115	0.1055
Relative error (%) between theory vs simulation	0.21	0.50	0.84	1.20	0.01	0.05	1.28
Relative error (%) between theory vs measurement	5.41	4.91	3.21	5.74	16.83	20.09	15.46

Moreover, we can point out that the simulated FoM_n is much closer to the calculated one with 1.28% maximum shift. Furthermore, the measured results have discrepancies from 5% to 15.5%.

Based on such finding of deviations, open questions are raised about the sensitivity of the BP NGD specifications in function of the component tolerances. This curious finding is answered in the present study by means of UA. The BP NGD performance sensitivity linked to the imperfections of the R, L and C component fabrication is materialized in the next section via theoretical approaches and comparison with ADS® parametric AC simulations.

VI. UA OF THE BP NGD CIRCUIT WITH RESPECT TO THE R, L AND C COMPONENT IMPERFECTIONS

In the present section, the UA regarding the R, L and C component imperfections by means of theoretical and simulation approach will be investigated. Doing this, the analytical expressions of the NGD parameters with respect to lumped R, L, and C tolerances are established. Then, the numerical validations are discussed.

A. THEORETICAL EXPRESSIONS OF THE BP NGD SPECIFICATIONS UA

Due to the fabrication imperfection, it is well known that passive components can undergo variations depending on their nature using conditions, the mathematical variations:

$$\Delta x = \{\Delta R, \Delta R_n, \Delta L_n, \Delta C_n\} \quad (41)$$

are considered respectively on each passive component constituting the NGD cell. Computations were carried out using the principle of maximizing margins of error. It is noteworthy that our approach considers the absolute value of the inputs that each component involved in the NGD specifications, f_n , T_n , GD_n and BW_n . By considering the previously established quantities expressed in equations (5), (17), (18) and (21), the analytical expressions of the NGD specification UAs are given as follows:

$$\frac{\Delta f_n}{f_n} \leq \frac{\frac{\Delta L_n}{L_n} + \frac{\Delta C_n}{C_n}}{2} \quad (42)$$

$$\frac{\Delta T_n}{T_n} \leq \frac{R_n}{R_n + R} \left(\frac{\Delta R}{R} + \frac{\Delta R_n}{R_n} \right) \quad (43)$$

$$\frac{\Delta GD_n}{GD_n} \leq \left(\frac{R}{R_n + R} \right) \frac{\Delta R}{R} + \left(\frac{R_n + 2R}{R_n + R} \right) \frac{\Delta R_n}{R_n} + \frac{\Delta L_n}{L_n} \quad (44)$$

$$\frac{\Delta BW_n}{BW_n} \leq \frac{1}{2} \left(\frac{R_n}{R_n + R} \right) \frac{\Delta R}{R} + \left(\frac{R_n + 2R}{2(R_n + R)} \right) \frac{\Delta R_n}{R_n} + \frac{\Delta C_n}{C_n} \quad (45)$$

$$\frac{\Delta FoM_n}{FoM_n} \leq \frac{1}{2} \left| \frac{R_n + 2R}{R_n + R} \right| \left(\frac{\Delta R}{R} + \frac{\Delta R_n}{R_n} \right) \quad (46)$$

Relations (42) to (46) are commonly published in the literature, especially considering uncertainty management methods such as GUM (Guide to the expression of

uncertainty in measurement) [37]. To verify the relevance of these analytical formulas, numeric applicative studies with relative tolerances denoted $\Delta x/x$ equal to 1%, 2% and 5% are proposed in the next paragraph.

B. BP NGD PARAMETERS UA ON A VARIATION RANGE OF RLC COMPONENTS VALUES

This subsection analyses the 2-D mapping behavior of the BP NGD parameters. For each component, we consider the variation range:

- From 1 mΩ to 1 kΩ for R_n ,
- From 1 mΩ to 1 kΩ for R ,
- And from 1 nH to 50 nH for L_n (which is also equivalent to C_n).

Figs. 8, 9, and 10 represent the ADS® simulated results of VTF magnitude, phase, and GD mappings with respect to both frequency and each R_n , R , L_n and C_n elements.

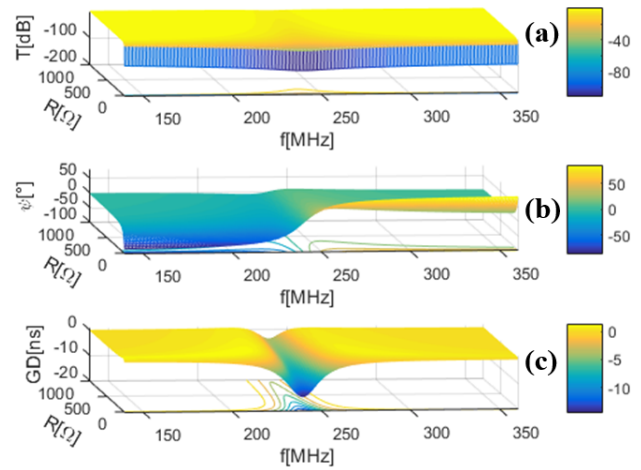


FIGURE 8. Variations of the VTF magnitude, phase and GD with respect to resistance R variation in the range from 1 mΩ to 1 kΩ.

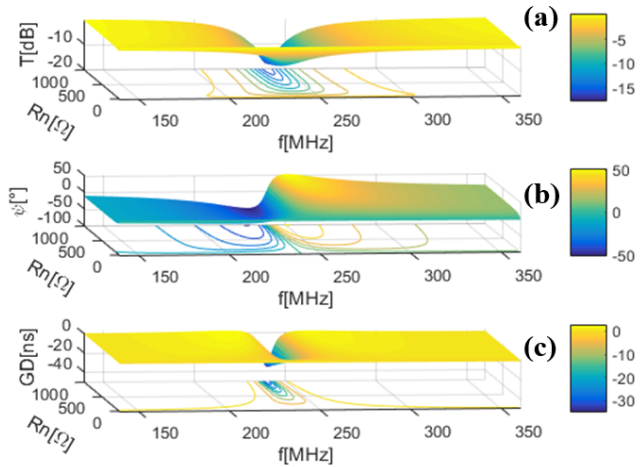


FIGURE 9. Variations of the VTF magnitude, phase and GD with respect to resistance R_n variation in the range from 1 mΩ to 1 kΩ.

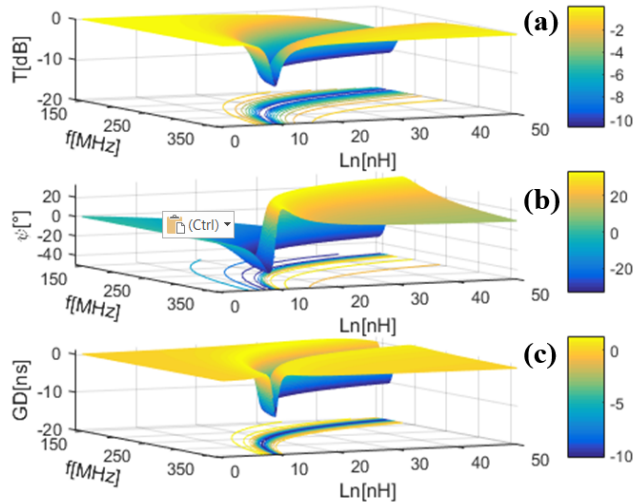


FIGURE 10. Variations of the VTF magnitude, phase and GD with respect to inductance L_n variation in the range from 1 nH to 50 nH.

From these 2-D plots, we can point up that:

- In Fig. 8(a) and 8(b), we can remark the less influence of the output resistance R on $T(\omega)$ and ψ

(in °). While, as illustrated in Fig. 8(c), the GD tends to increase with the output resistance R .

- Fig. 9 represents the cartographies of the NGD parameters versus frequency and R_n . The magnitude (resp. GD) tends to decrease when R_n values are in its lower range as seen in Fig. 9(a) (resp. 9(c)).
- We emphasize from Fig. 10, we can denote that the NGD parameters decrease when L_n also decreases.

C. NUMERIC APPLICATION

The present UA numeric application consolidates the BP NGD performance variation and sensitivity in function of R , L and C component fabrication imperfections. The present UA applicative study is based on the comparison between the calculated and simulated results.

1) UA CALCULATED RESULTS

Table IV, Table V and Table VI highlight the influence of tolerances of R , R_n , and L (or C) element values on each BP NGD parameters. We consider in the present case of study the relative tolerances 1%, 2% and 5%.

TABLE IV. UAs of NGD specifications according to variations of R

Specification	Theory	Uncertainty [%]					
		$R \pm 1\%$		$R \pm 2\%$		$R \pm 5\%$	
		Theory	ADS®	Theory	ADS®	Theory	ADS®
T_n	0.706	0.608	1.412	1.361	3.529	3.401	
GD_n	0.294	0.296	0.588	0.591	1.471	1.478	
BW_n	0.353	0	0.706	0	1.765	2.392	
FoM	0.647	0.383	1.294	0.761	3.235	0.564	

TABLE V. UAs of NGD specifications according to variations of R_n

Specification	Theory	Uncertainty [%]					
		$R_n \pm 1\%$		$R_n \pm 2\%$		$R_n \pm 5\%$	
		Theory	ADS®	Theory	ADS®	Theory	ADS®
T_n	0.706	0.680	1.412	1.361	3.529	3.401	
GD_n	1.294	1.281	2.588	2.562	6.471	6.502	
BW_n	0.647	2.392	1.294	2.392	3.235	5.263	
FoM	0.647	1.815	1.294	1.254	3.235	2.535	

TABLE VI. UAs of NGD specifications according to variations of L_n (or C_n)

Specification	Uncertainty [%]					
	L_n or $C_n \pm 1\%$		L_n or $C_n \pm 2\%$		L_n or $C_n \pm 5\%$	
	Theory	ADS®	Theory	ADS®	Theory	ADS®
f_n	0.5	0.458	1	0.916	2.5	2.291
T_n	0	0	0	0	0	0
GD_n	1	0.099	2	0.099	5	0.099
BW_n	1	0.239	2	2.632	5	5.263
FoM	0	0.141	0	2.536	0	5.170

The following remarks can be emphasized from the numerical application:

- Table IV and Table V show that the T_n uncertainty depends only to the resistive parameters (R and R_n) but not to the reactive components. We can underline that R and R_n have the same influence on the uncertainty of T_n . A 5% relative tolerance on R and R_n , induces a maximum uncertainty of VTF magnitude less than 3.53%.
- It is important to recall that in difference to the case of f_n , as pointed out in equation (25), the NGD center frequency f_n depends only on the L and C parameters. It means that the f_n UA is only in function of the L and C tolerances. As seen in Table VI, we remark that when the relative tolerances are fixed to 5 %, the f_n UA is around 2.5%.
- The NGD value GD_n appears to be the most sensitive NGD parameters to the variations of the lumped elements. A 5% relative tolerance on R and R_n implies respectively relative variation more than 1.4%, and 6.5% around the GD. While a 2% relative tolerance on L and C elements generates an uncertainty of 2% around the GD.
- The observation of Table VI, allows to notice that the NGD bandwidth and FoM are also sensitive to the variation of each circuit component. A 5% relative tolerance of the inductance and the capacitance causes an uncertainty more than 5% around the NGD bandwidth and FoM.

2) DISCUSSION ON THE UA CALCULATED AND SIMULATED RESULTS

The previous numeric applications on UA revealed the effect of RLCP POC and prototype lumped component tolerances. The variations of the BP NGD parameters enable to quantify the sensitivity in function of the component fluctuation.

We noticed from the different calculations:

- How the NGD parameter uncertainties vary with respect to the tolerances. Furthermore, we can also predict in certain cases that the NGD parameter

relative variations are not changing non-linearly. In some cases, they appear to change following hyperbolic variation.

- It is also noticed that GD_n , BW_n and FoM parameters are more sensible to the R , R_n , L_n and C_n component imperfections. Under relative tolerance of 5%, the variation of R_n induces more impact on all NGD parameters than the other lumped elements. However, it is important to precise that the proposed UA of RLCP circuit BP NGD parameters is done by considering R, L and C components changing independently.
- Of course, at this stage of study, most design electronic engineers may ask about the undesirable effects on the BP NGD parameters related to the superposition of tolerances of all lumped components. This curious question constitutes our ongoing future research work, we plan to study simultaneous variation of several parameters by means of equations (42) to (46).

VII. CONCLUSION

An UA of the BP NGD passive topology ever being done before is developed. The considered topology is essentially comprised of RLCP-network cell.

The BP NGD circuit theory is established from VTF in function of frequency variation and RLC passive circuit elements. The analytical BP NGD characterization of the NGD specifications in function of the R, L and C component values is developed. The main specifications of the NGD circuit as the NGD center frequency, NGD value, NGD bandwidth, attenuation and even the BP NGD FoM were investigated. The analytical expressions of the NGD specifications have been established. It was demonstrated how the BP NGD FoM is maximized for a certain value of the resistances of the RLCP NGD circuit. This optimal FoM corresponds to 1/3 attenuation (approximately -9.54 dB).

Three different approaches based on theoretical, simulation and experimental validations were undertaken.

The simulation was carried out with the ADS® commercial tool. The relevance of the BP NGD theory is validated with excellent agreement with simulations and measurements.

The UA investigations show that the BP NGD circuit attenuation is sensitive to resistance variations. The same behavior is found for the NGD value and NGD bandwidth but they are literally sensitive to reactive components variations. The performed UAs enable to understand how sensitive is our BP NGD topology with respect to the component tolerances.

In the future, the present BP NGD investigation could contribute in particular to the improvement of the electronic and communication system by:

- Compensating the transmission signal delay [22,29-31],
- Reducing undesirable resonance effect against PCB electromagnetic compatibility (EMC) issues [38-39],
- And to design frequency independent NGD phase shifter [40].

To develop such a BP NGD circuit application, we can take care on the UA with the used component imperfection considerations.

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